

Understanding ODD: What it is and isn't! ISO 34503 perspective

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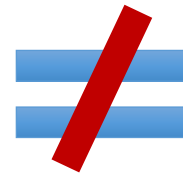
ISO 34503: Motivation

Full title:

Road Vehicles - Taxonomy for Operational Design Domain for an Automated Driving System

Why is ODD important?

- Number of miles driven?
- Types of scenarios experienced?



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ISO 34503: Background and Current Status

Full title:

Road Vehicles - Taxonomy for Operational Design Domain for an Automated Driving System

ISO 34503: Background and Current Status

Full title:

Road Vehicles - Taxonomy for Operational Design Domain for an Automated Driving System

- Under the aegis of ISO TC22 SC33 WG9
- Sep 2019 Kick-off
- Experts from **all over the world**
- **DIS stage** – Draft International Standard (publicly available)

ISO 34503: Scope

*“This document specifies the **requirements for the hierarchical taxonomy** for specifying operating conditions which enable the definition of an Operational Design Domain (ODD) of an Automated Driving System (ADS). This document also specifies **requirements for the definition format** of an ODD using the taxonomy. The ODD comprises specific conditions (which include the static and dynamic attributes) within which an ADS is designed to function....”*

ISO 34503: Scope

*“This document specifies the **requirements for the hierarchical taxonomy** for specifying operating conditions which enable the definition of an Operational Design Domain (ODD) of an*

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*“....for use by organizations taking part in developing safety cases for automated vehicle, ..., for organizations **conducting trials, testing and commercial deployment**.... also for use by **manufacturers of Level 3/4 ADS** to define the ADS’ operating capability.*

ISO 34503: Scope

“This document specifies the **requirements for the hierarchical taxonomy** for specifying operating conditions which enable the definition of an Operational Design Domain (ODD) of an

Autonomous Road Vehicle (ARV) for use by organizations taking part in developing safety cases for automated vehicle, ..., for organizations **conducting trials, testing and commercial deployment**.... also for use by the **manufacturers of Level 2/4 ADS** to define the ADS' operating capabilities

“....It is also of interest to **insurers, regulators, service providers, national, local and regional governments** to enable them to understand possible ADS deployments and capabilities....”

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ODD, Scenarios and more...



For more on
Curious case of ODD:
<https://bit.ly/CuriousCaseODD>

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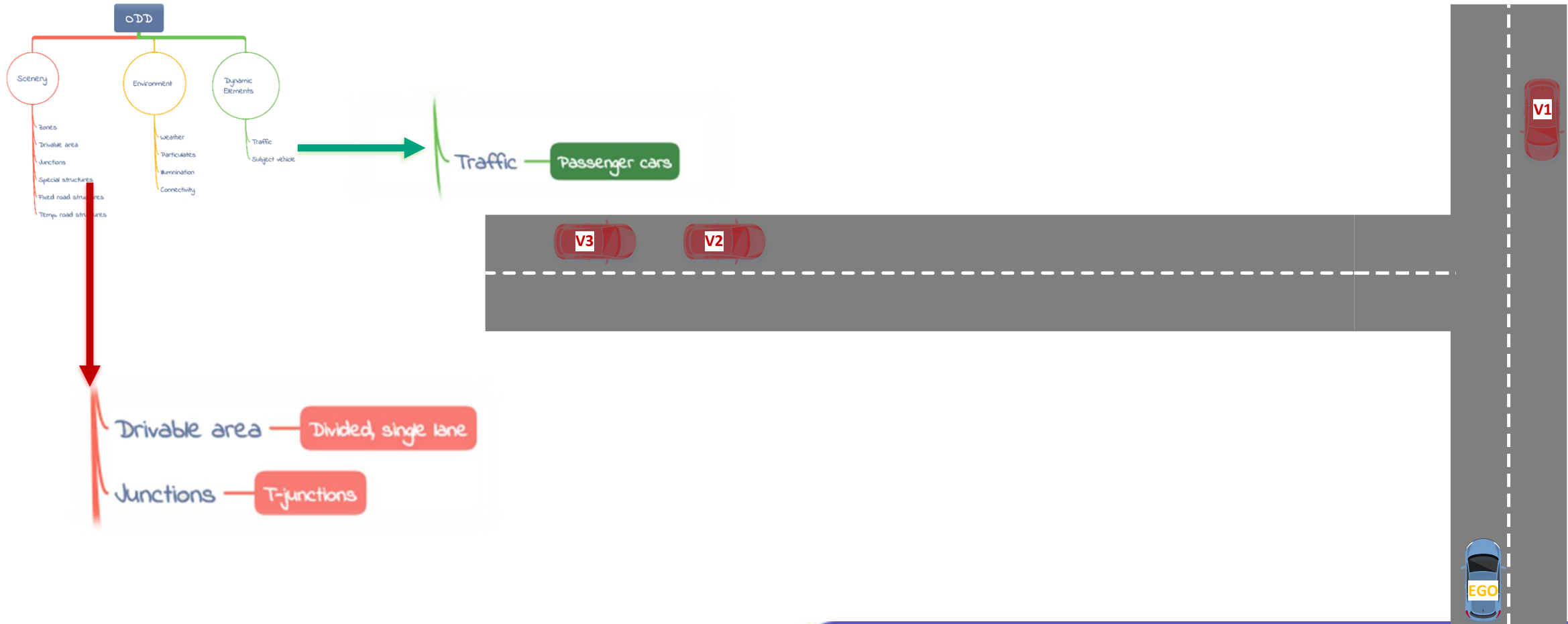


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ISO 34503: ODD and Scenario



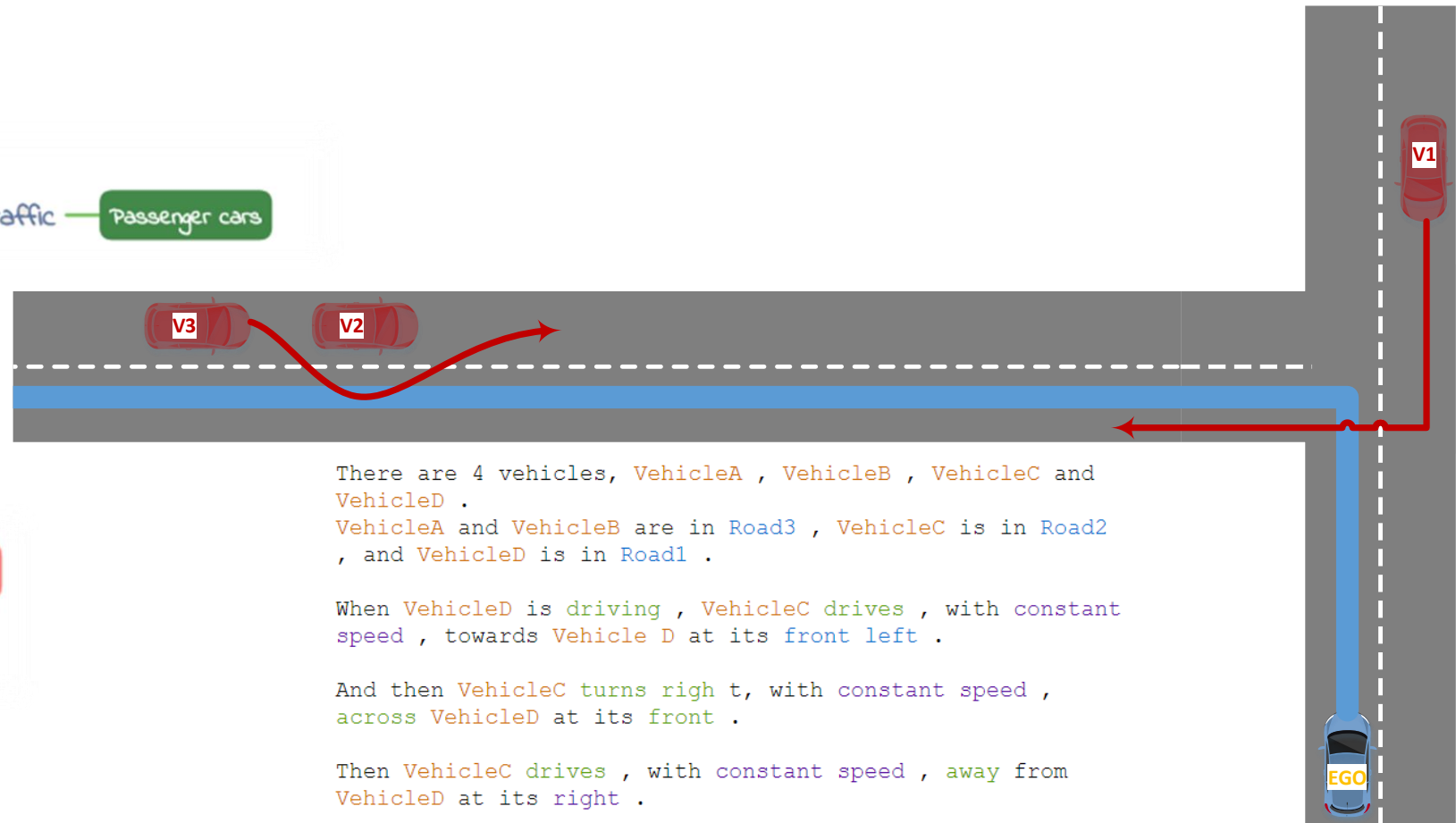
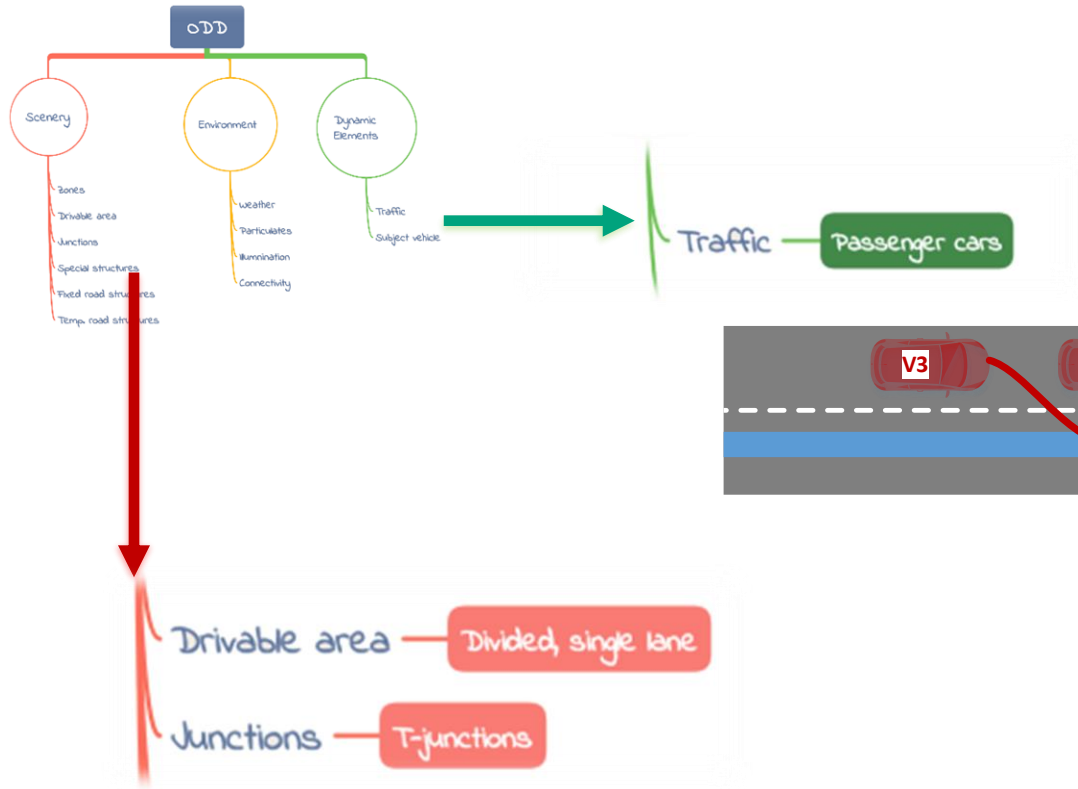
ISO 34503: ODD and Scenario



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ISO 34503: ODD and Scenario



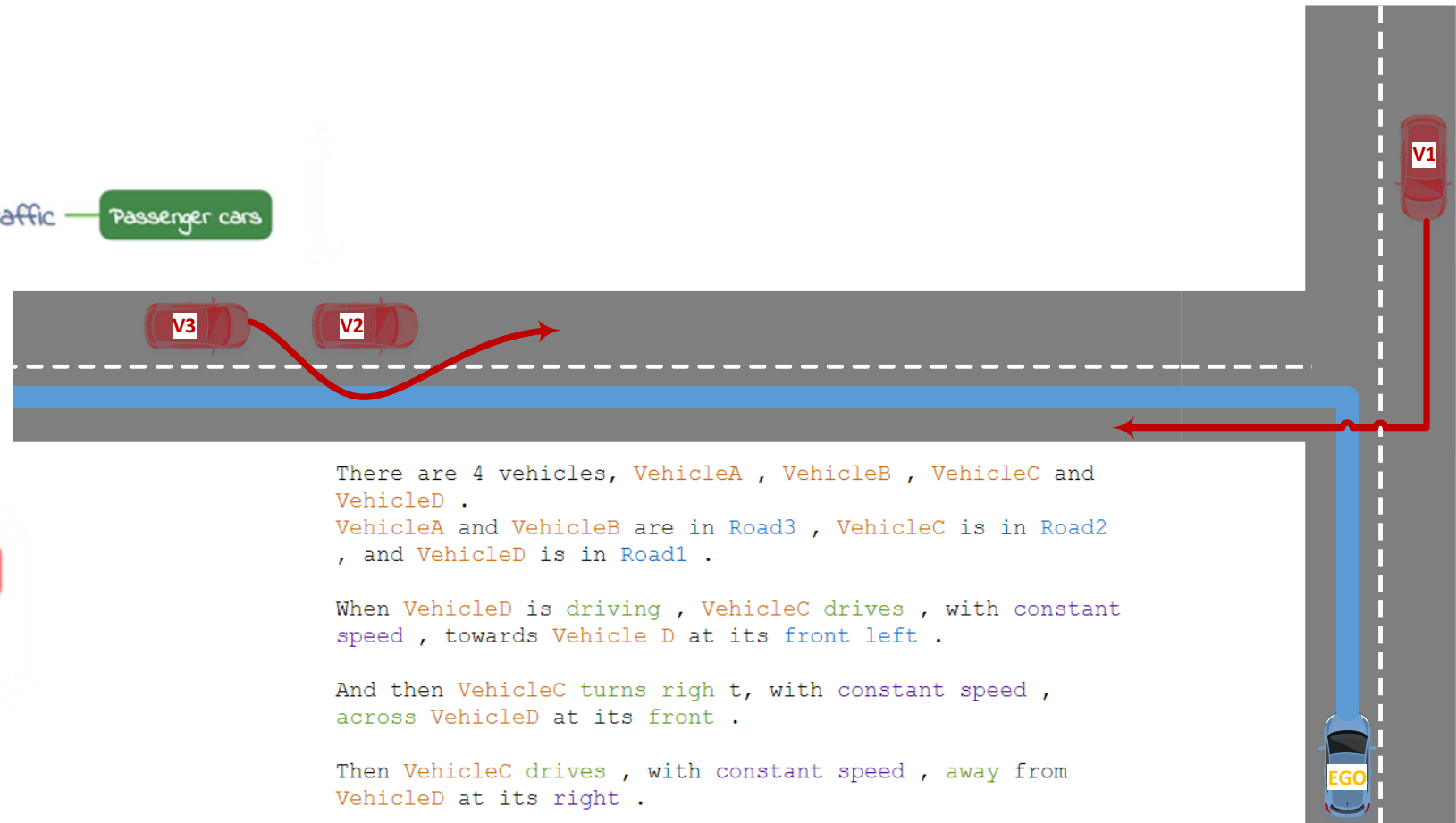
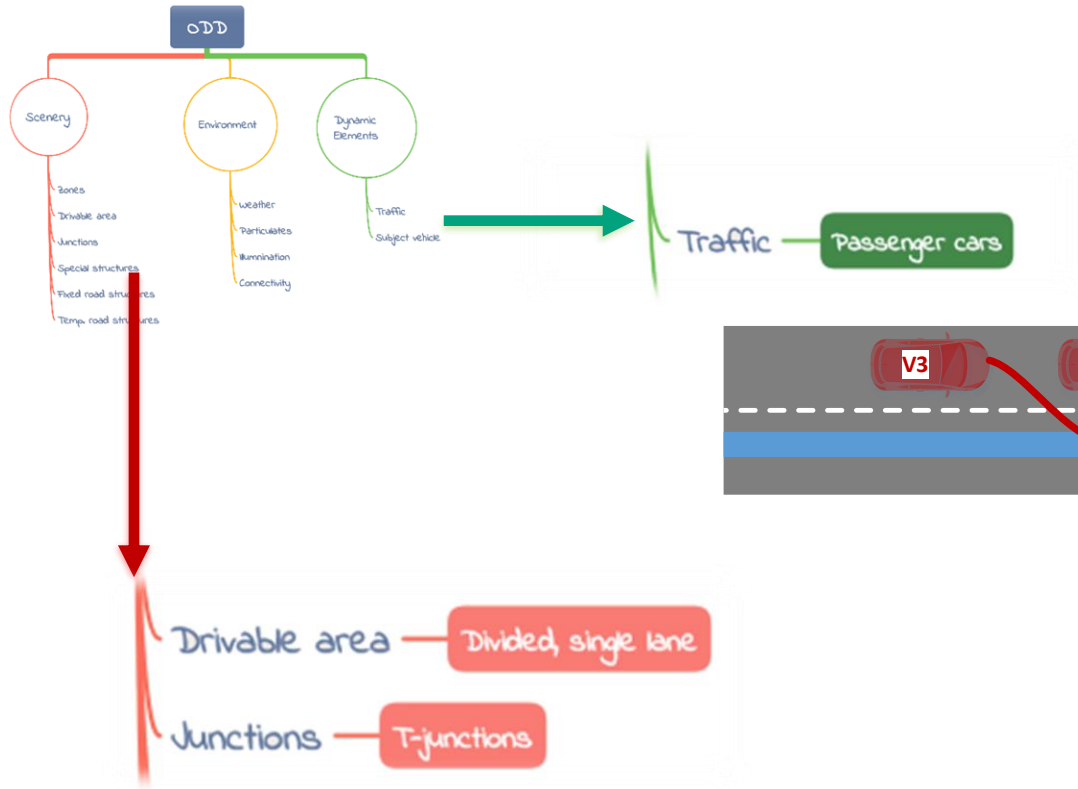
There are 4 vehicles, **VehicleA** , **VehicleB** , **VehicleC** and **VehicleD** .
VehicleA and **VehicleB** are in **Road3** , **VehicleC** is in **Road2** , and **VehicleD** is in **Road1** .

When **VehicleD** is driving , **VehicleC** drives , with constant speed , towards **Vehicle D** at its front left .

And then **VehicleC** turns right , with constant speed , across **VehicleD** at its front .

Then **VehicleC** drives , with constant speed , away from **VehicleD** at its right .

ISO 34503: ODD and Scenario



There are 4 vehicles, `VehicleA` , `VehicleB` , `VehicleC` and `VehicleD` .
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For more on Curious case of ODD:
<https://bit.ly/CuriousCaseODD>

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ODD and Operational Domain (OD)

WORLD

ODD and Operational Domain (OD)

WORLD = OD

Area 1

ODD and Operational Domain (OD)

WORLD = OD

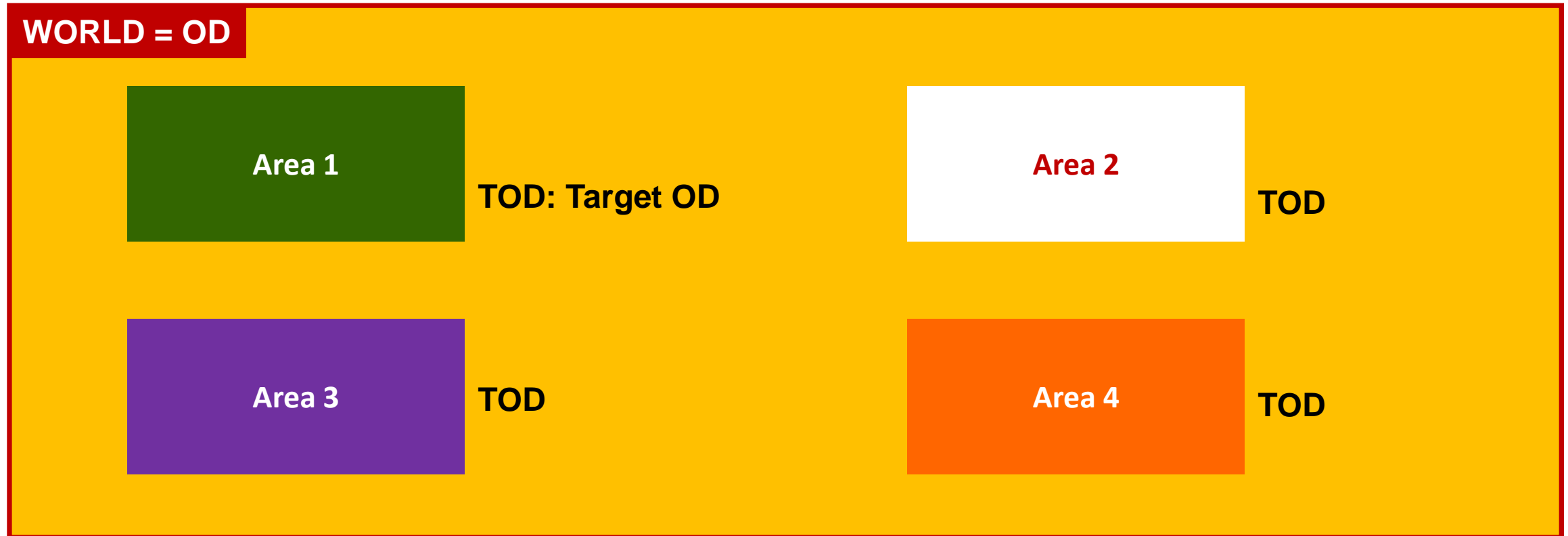
Area 1

Area 2

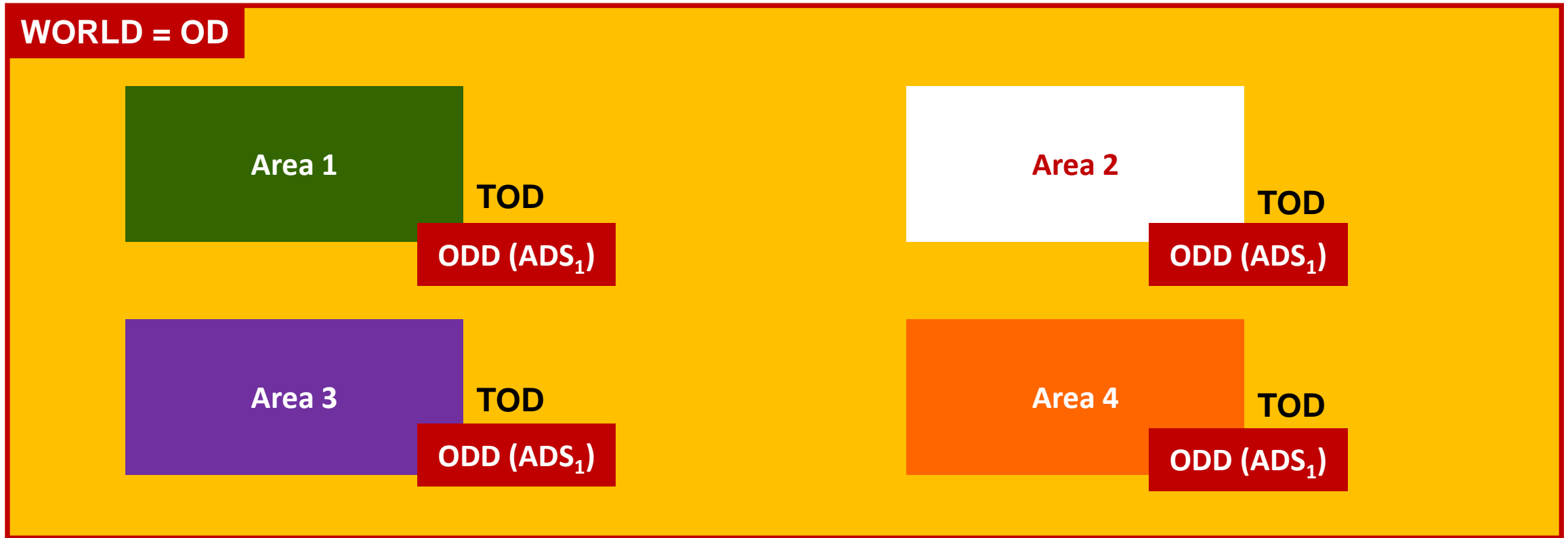
Area 3

Area 4

ODD and Operational Domain (OD)

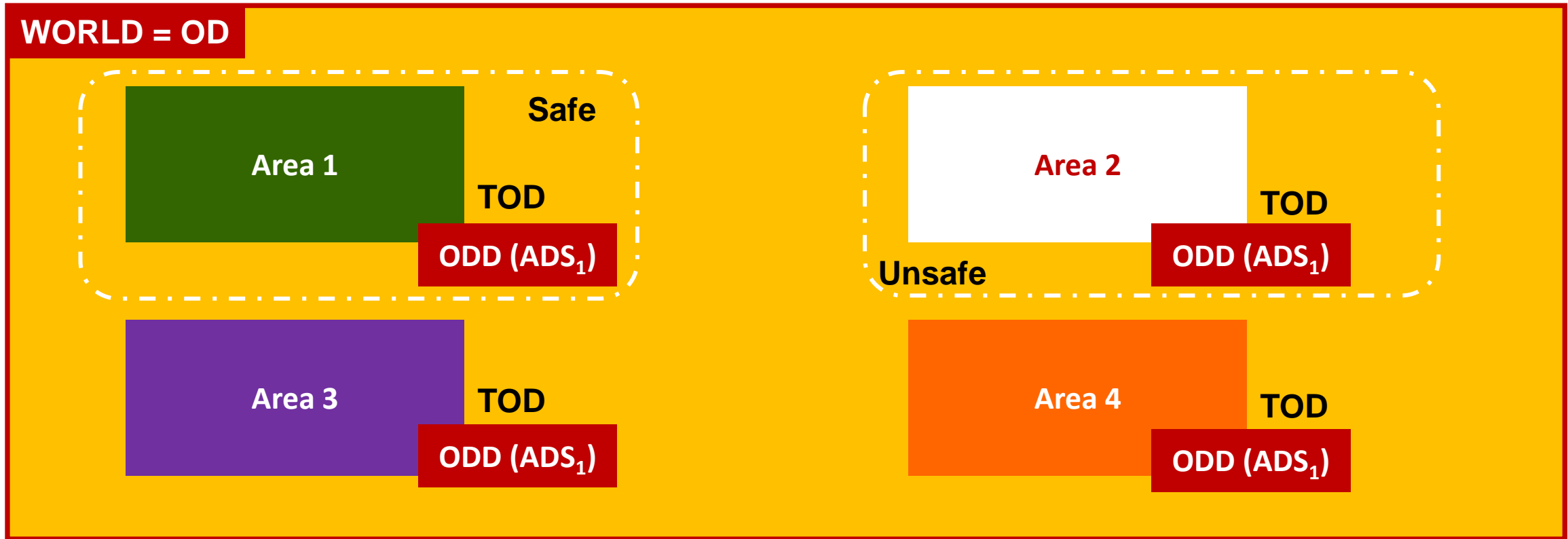


ODD and Operational Domain (OD)



ODD (ADS₁) = Safe

ODD and Operational Domain (OD)



ODD (ADS₁) = Safe

ISO 34503: Doc structure

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5 Operational Design Domain (ODD) and Target Operational Domain (TOD)	
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8 ODD Taxonomy	
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11 Dynamic elements.....	
12 ODD definition format	

ISO 34503: Doc structure

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12 ODD definition format	

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6 ODD and scenario relationship.....
7 ODD requirements and application

ISO 34503: Doc structure

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7 ODD req	9 Scenery elements
8 ODD Tax	10 Environmental conditions.....
9 Scenery	11 Dynamic elements.....
10 Environ	
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12 ODD definition format	

ODD Taxonomy

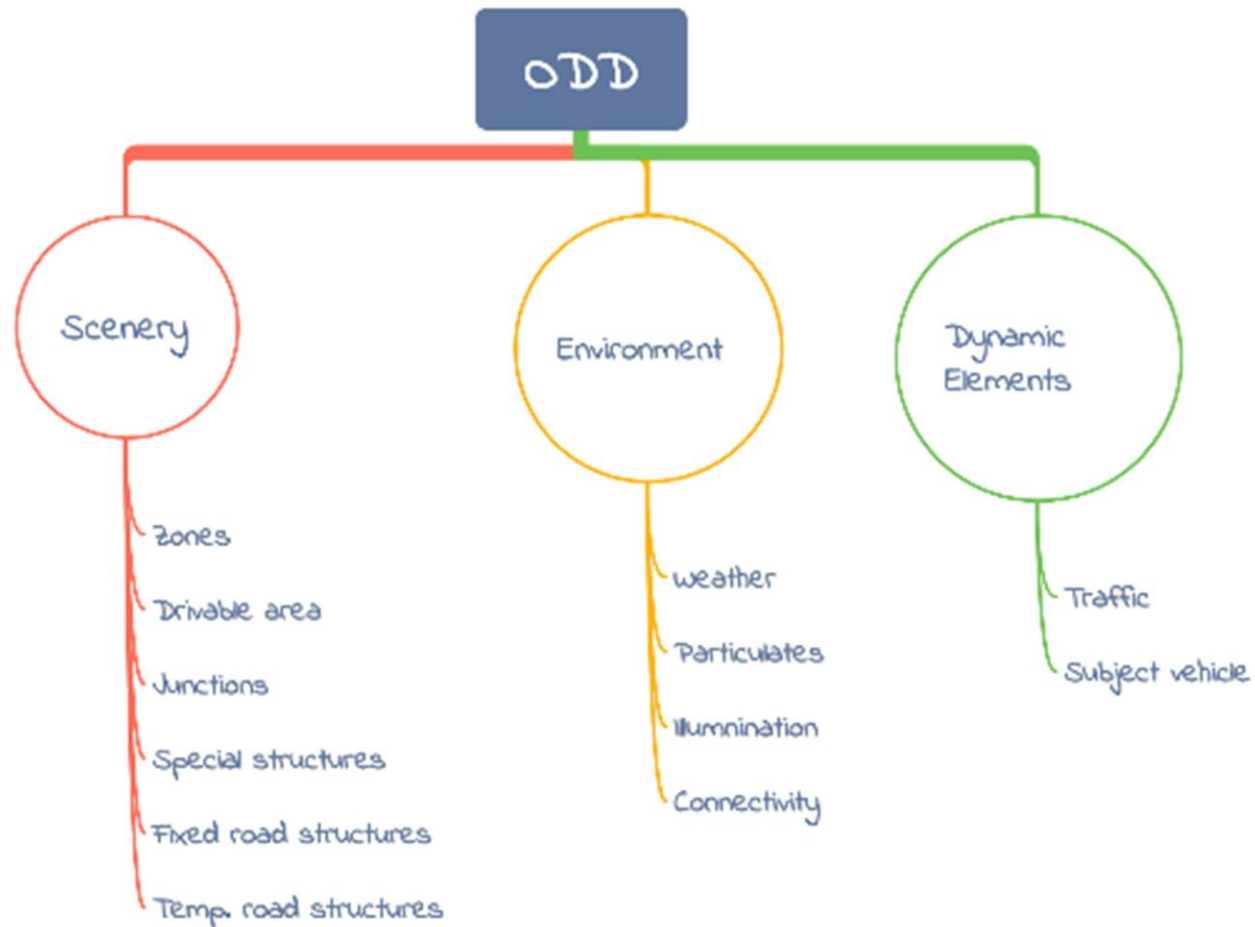
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11 Dynamic elements	
12 ODD definition format	

ODD Format

12 ODD definition format

ISO 34503: Taxonomy



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ISO 34503: Format

- **Definition Format Type**

- Permissive
- Restrictive
- Default (don't care)

- **Human readability**

- **Qualifiers** (include, exclude and conditional)

ISO 34503: Format

■ Definition Format Type

- Permissive
- Restrictive
- Default (don't care)

■ Human readability

```
#Composition statements
Include geofenced areas is [predefined route]
Include regions or states is [Ottawa Canada]
Include zones are [regions or states, geofenced areas]
Cond_1 Conditional drivable area type are [minor roads, parking, shared space]
Cond_2 Conditional horizontal plane is [curved roads]
Exclude transverse plane is [divided]
Include
```

```
#Conditional statements
Cond_1 Include speed of subject vehicle for [minor roads] is [0,15 km/h]
Cond 1 Include speed of subject vehicle for [parking, shared space] is [0,10 km/h]
```

■ Qualifiers (include, exclude and conditional)

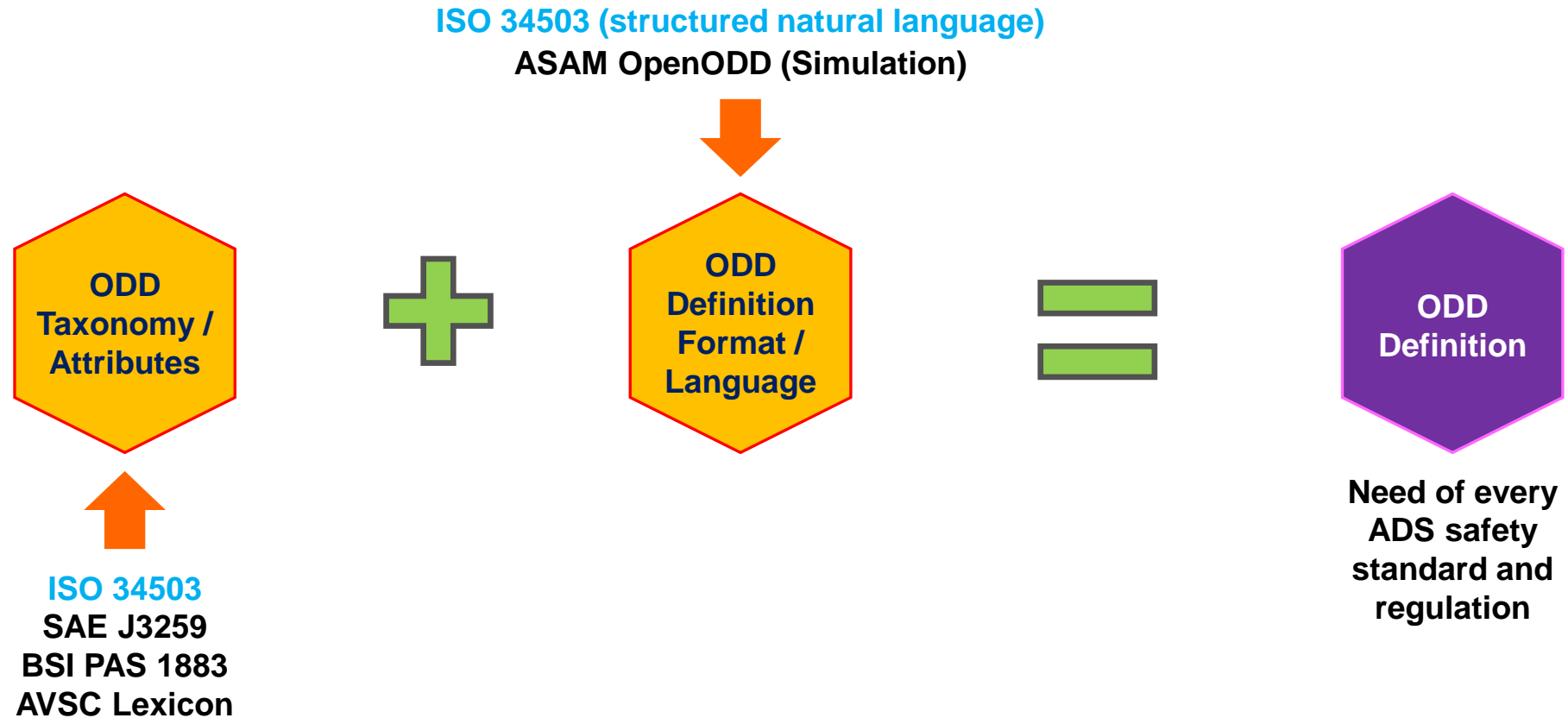
ODD Definition: Bringing things together...



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ODD Definition: Bringing things together...



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Summary

- Each aspect of safety assurance of ADS needs to consider its relationship with ODD.
- ISO 34503 will provide:
 - A **hierarchical taxonomy** for ODD definition
 - **Structured natural language format** for ODD definition
 - Clarification on **difference between ODD and scenarios**
- Success will be dependent upon suitable collaboration, data sharing and **common understanding**, nationally and internationally

Thank you... Discussion...

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@siddkhastgir 



ODD based Safety Assurance for Automated Driving Systems

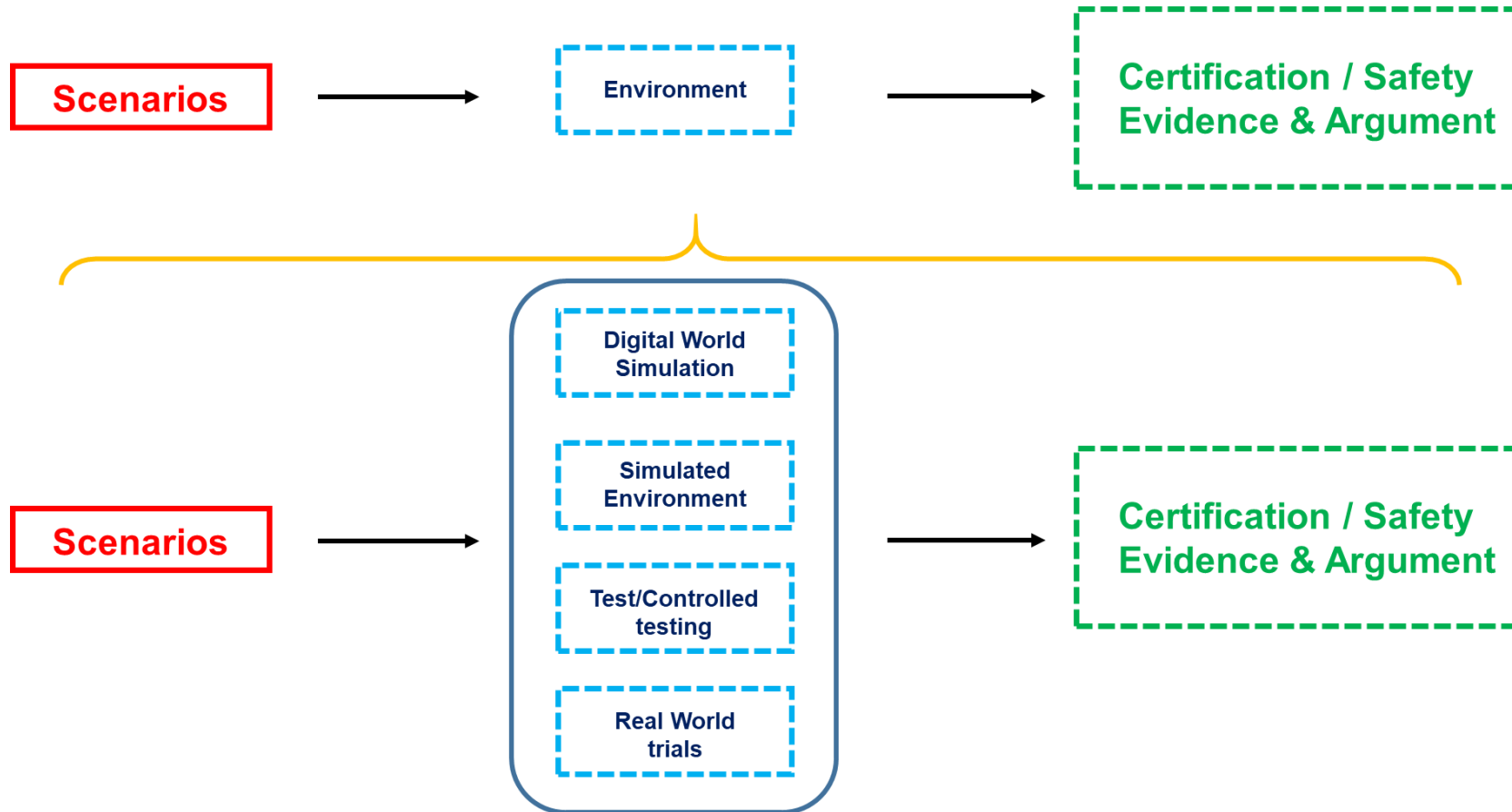
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Evaluation Continuum



Evaluation Continuum

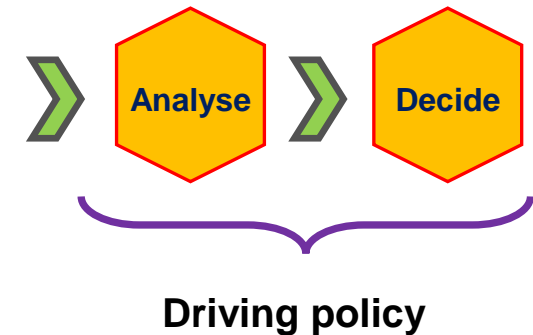
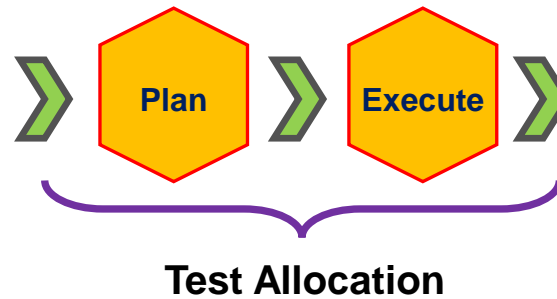


Evaluation Continuum

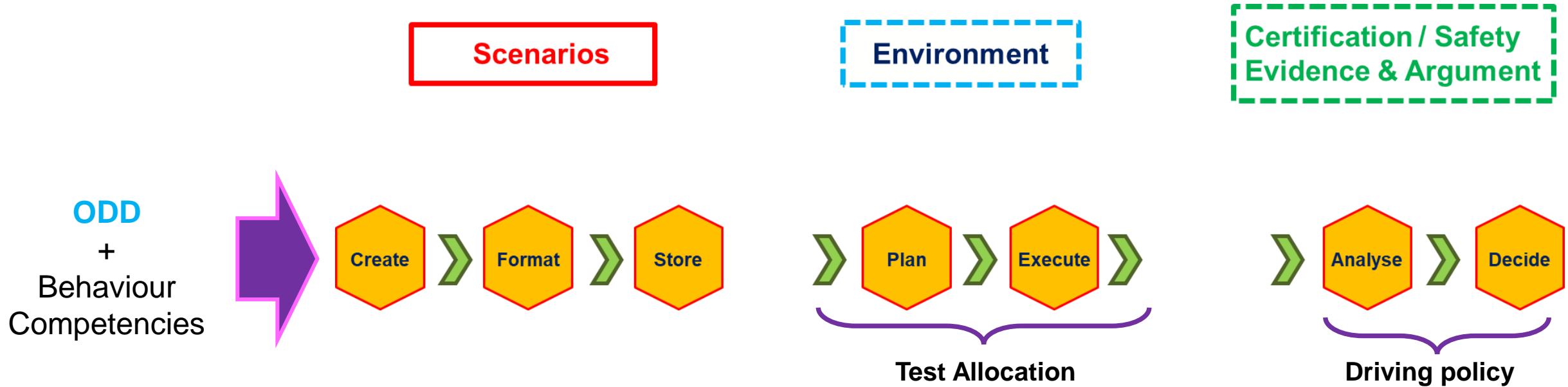
Scenarios

Environment

Certification / Safety
Evidence & Argument



ODD Based Scalable Safety Assurance Framework

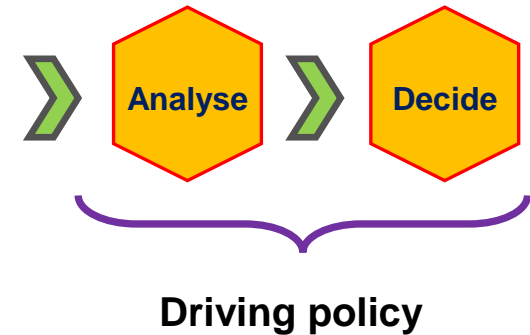
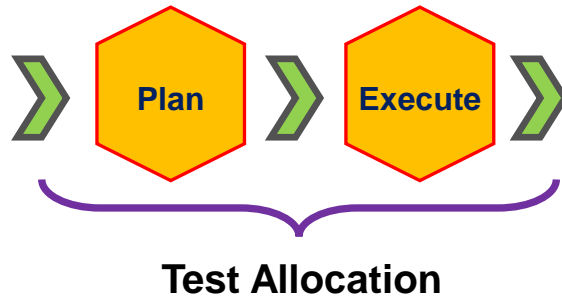


Evaluation Continuum

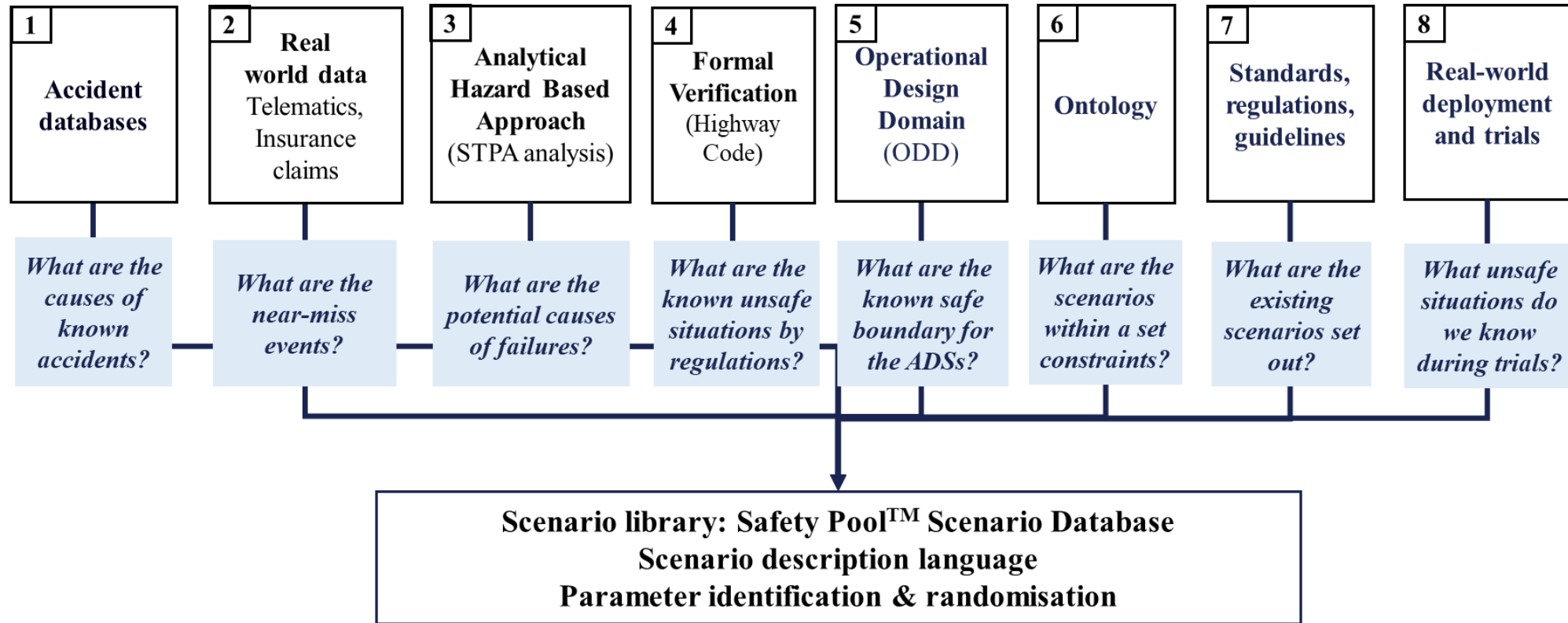
Scenarios

Environment

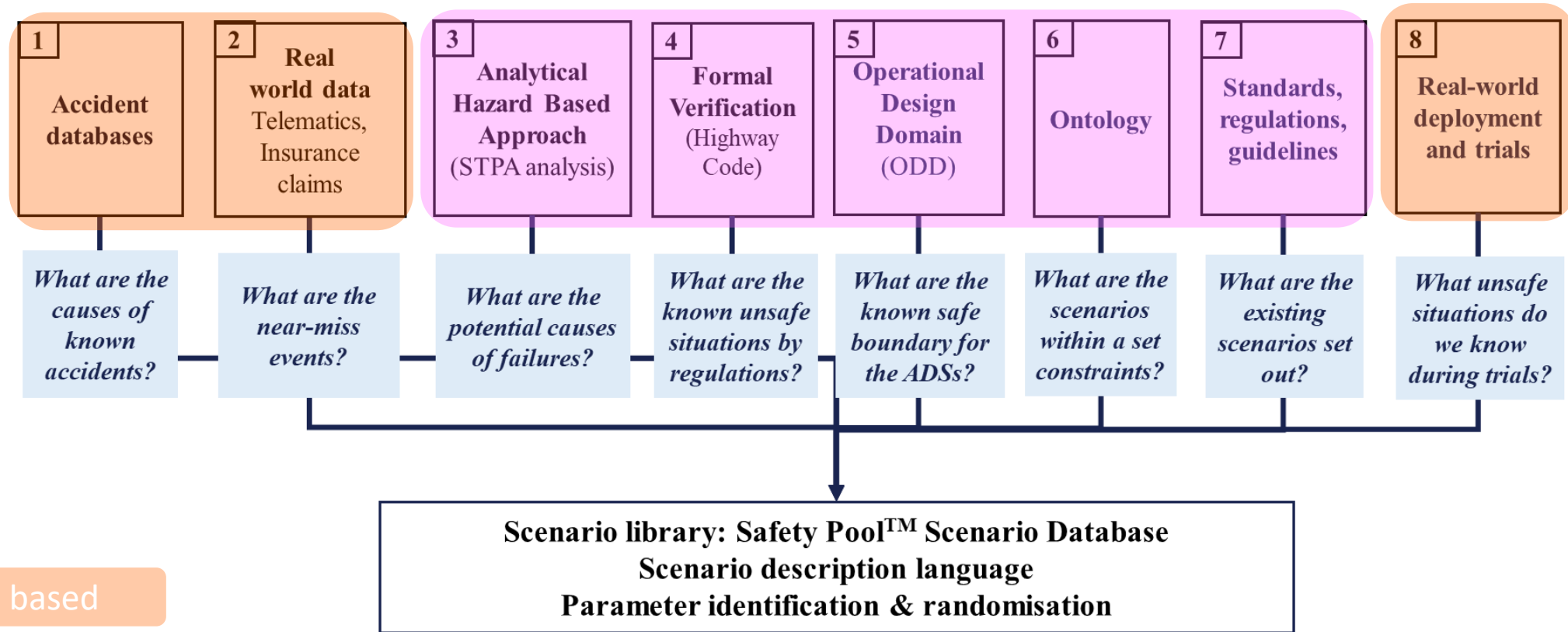
**Certification / Safety
Evidence & Argument**



Scenario: Create



Scenario: Create



Data based

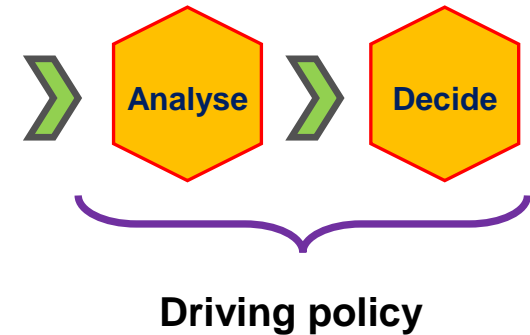
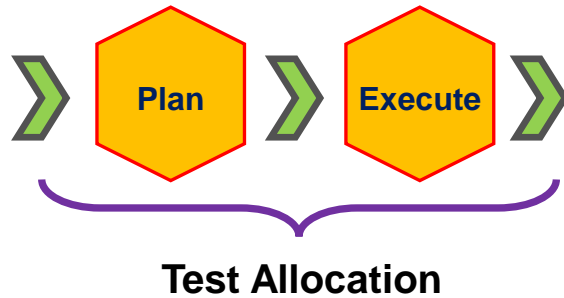
Knowledge based










Evaluation Continuum

Scenarios

Environment

Certification / Safety
Evidence & Argument



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-  Test Suites
-  Testbeds
-  Users
-  Roles
-  Settings
-  Audit Log

Welcome

The Safety Pool Database is an extensive collection of curated test scenarios which can be used for testing connected and autonomous driving technologies.

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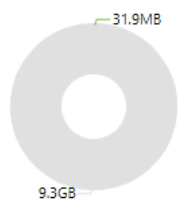
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World's Largest Public Scenario Database



File Storage

Quota used



In use: 31.9MB
Quota: 9.3GB
Quota used: 0%










License

Maximum Active Users
20

File Storage Quota
9.3GB

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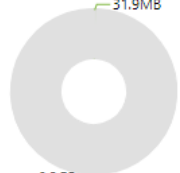
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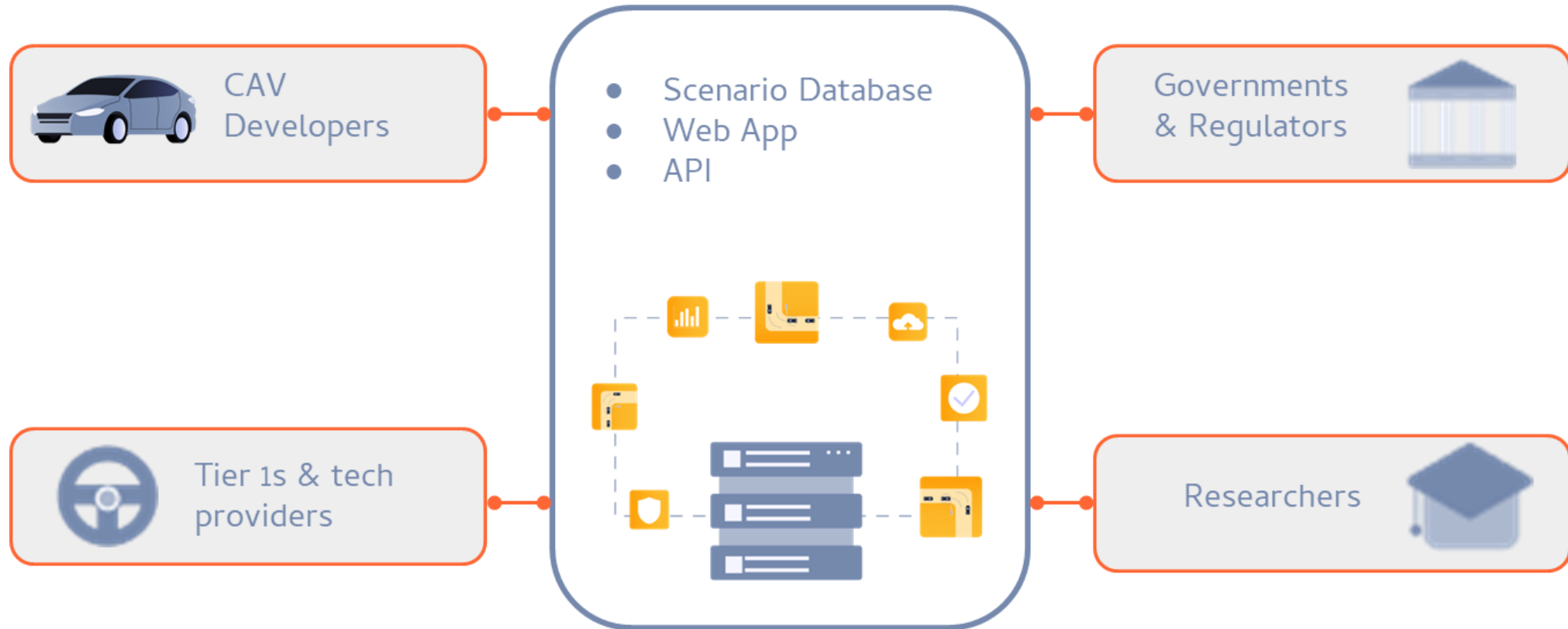
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Over 250,000 edge case scenarios

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What is the Safety Pool™ Scenario Database?



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← Scenario

Download Add to Test Suite

stat19_1_82482

Tags Definition Files Route Locations Versions

Scenery

- Broken line
- Contaminated
- Drive on left
- Lane dimensions [Width (m): 3.4 to 3.7]
- Level plane
- Normal roundabout
- Number of lanes [Lanes: 2]
- Radial road
- Shoulder (grass)
- Straights
- Traffic lane
- Undivided road
- Uniform surface

Environmental Conditions

- Cloudiness [Cloud cover (okta): 0 to 1]
- Day
- Sun elevation [Angle (degree): 10 to 30]
- Sun to the right
- Wind [Speed (m/s): 10.8 to 13.8]

Agents

- Cut-in
- Lane change left
- Vehicle

Meta Data

- Fatal collision

General

URN
d025e967-a9eb-452e-bd13-af66ec99a318

Library
[STATS-19](#)

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Version
1.0

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← Scenario

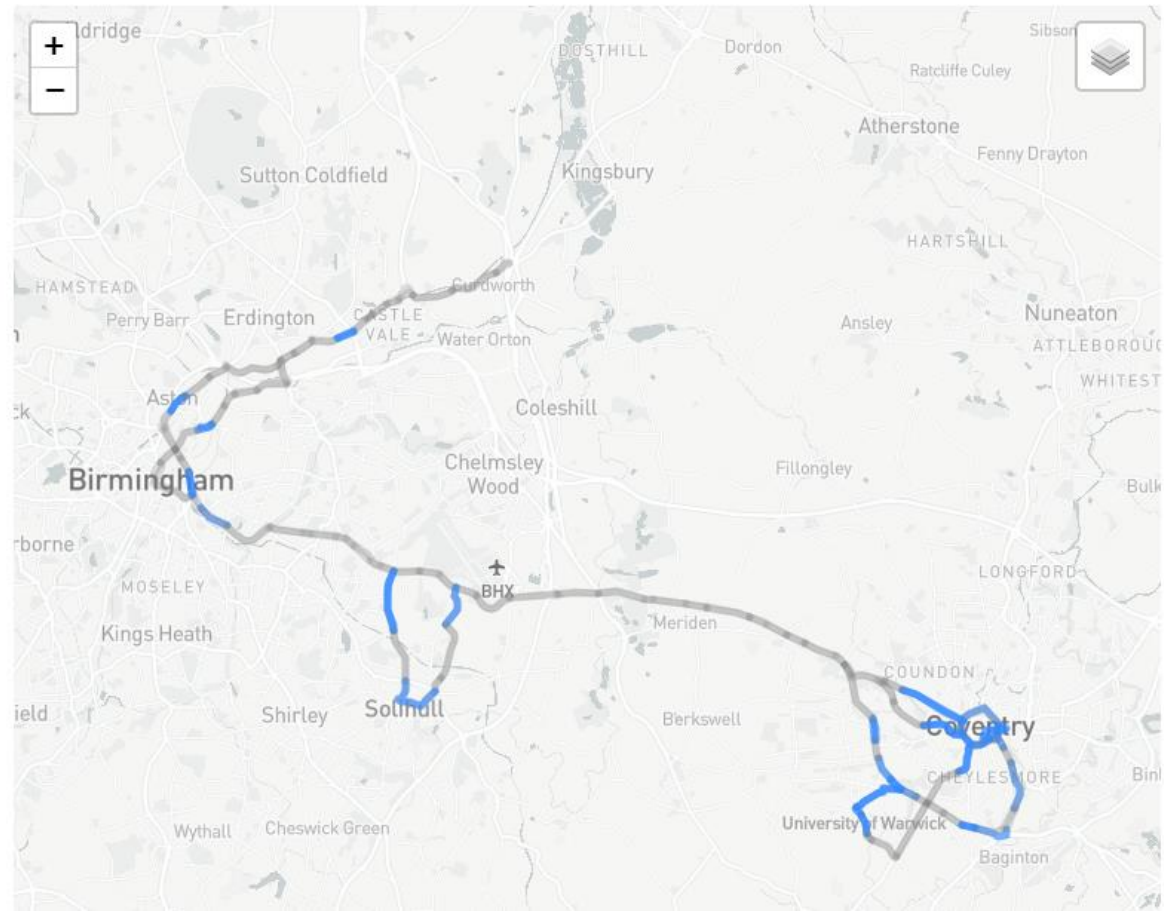
[Download](#) [Add to Test Suite](#)

stat19_1_82482

- Tags
- Definition
- Files
- Route Locations
- Versions


Midlands Future Mobility 38 possible testing locations found

This testbed does not support all of the tags for this scenario 




General



URN
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1.0

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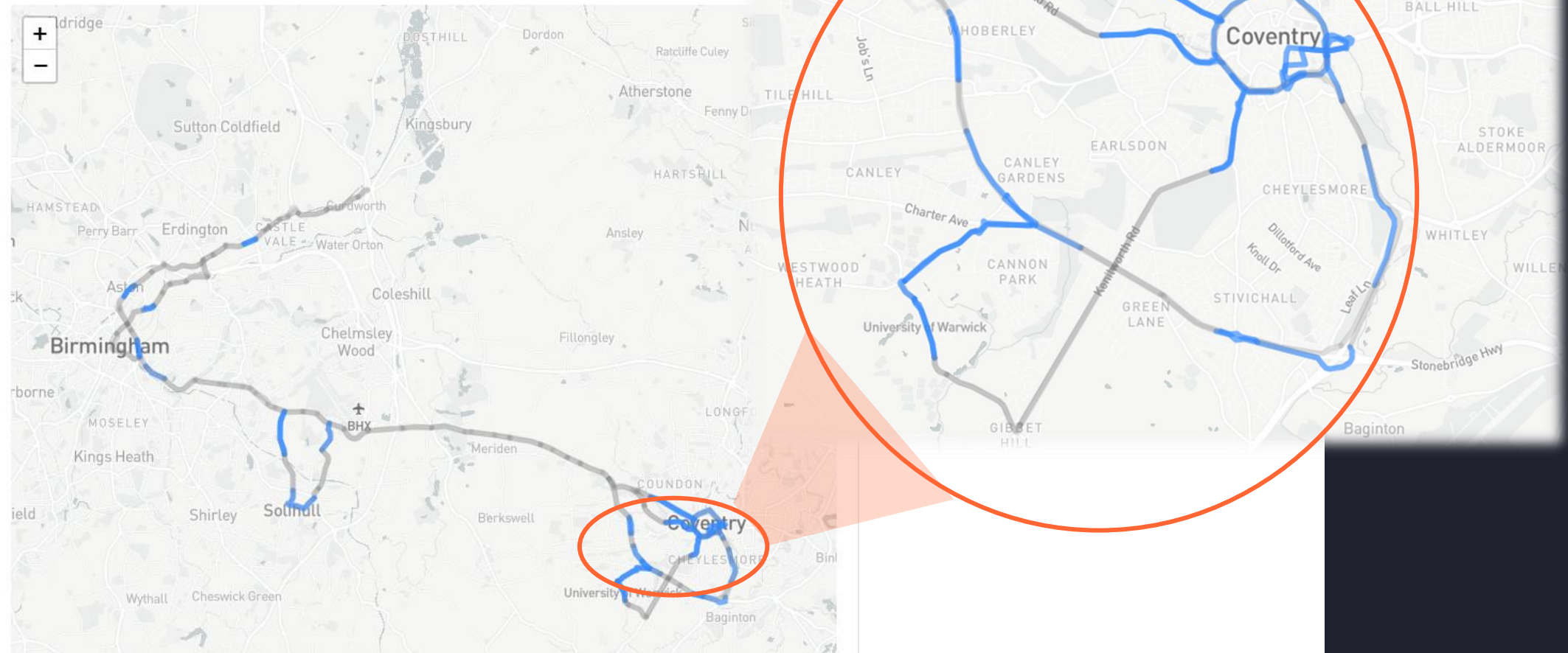
← Scenario

stat19_1_82482

- Tags
- Definition
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- Versions

Midlands Future Mobility 38 possible testing locations found

This testbed does not support all of the tags for this scenario i



← Scenario

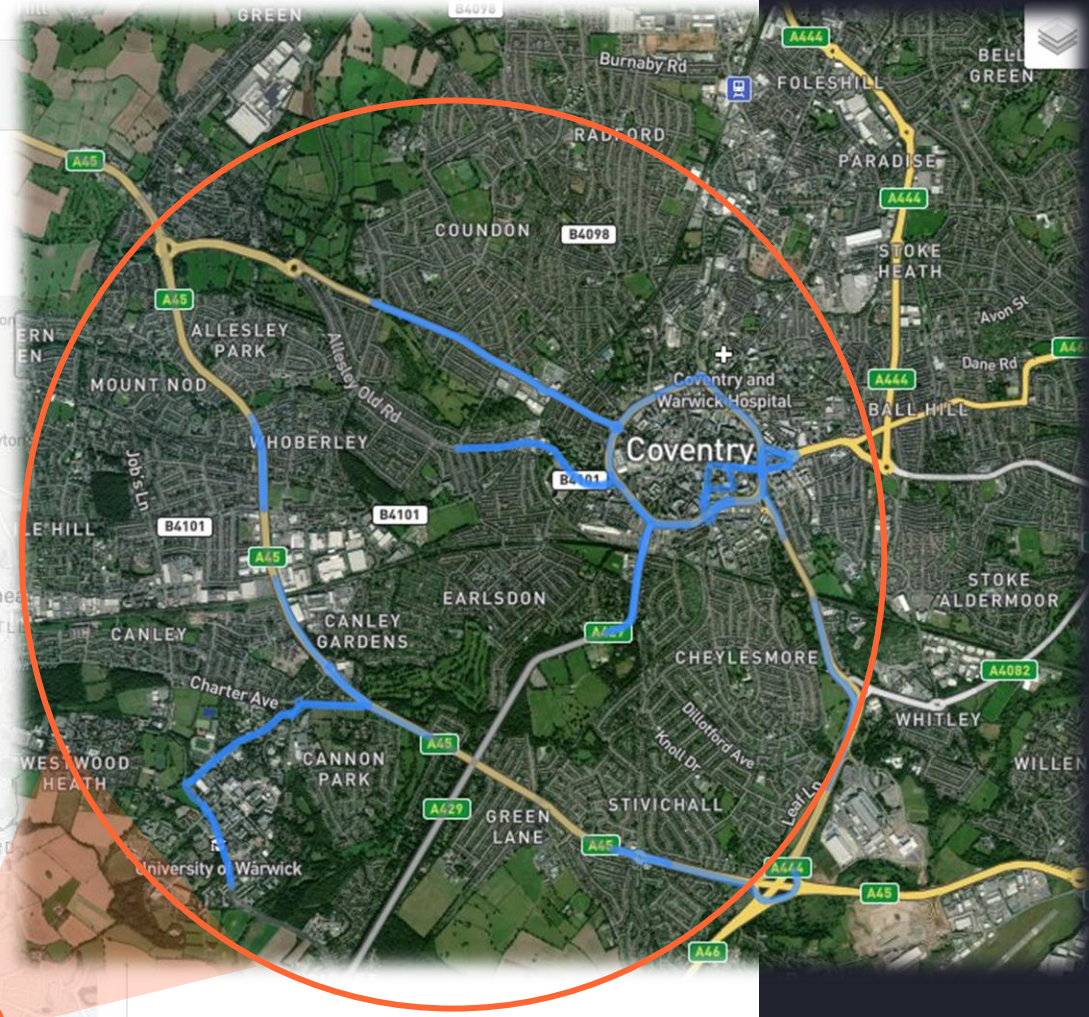
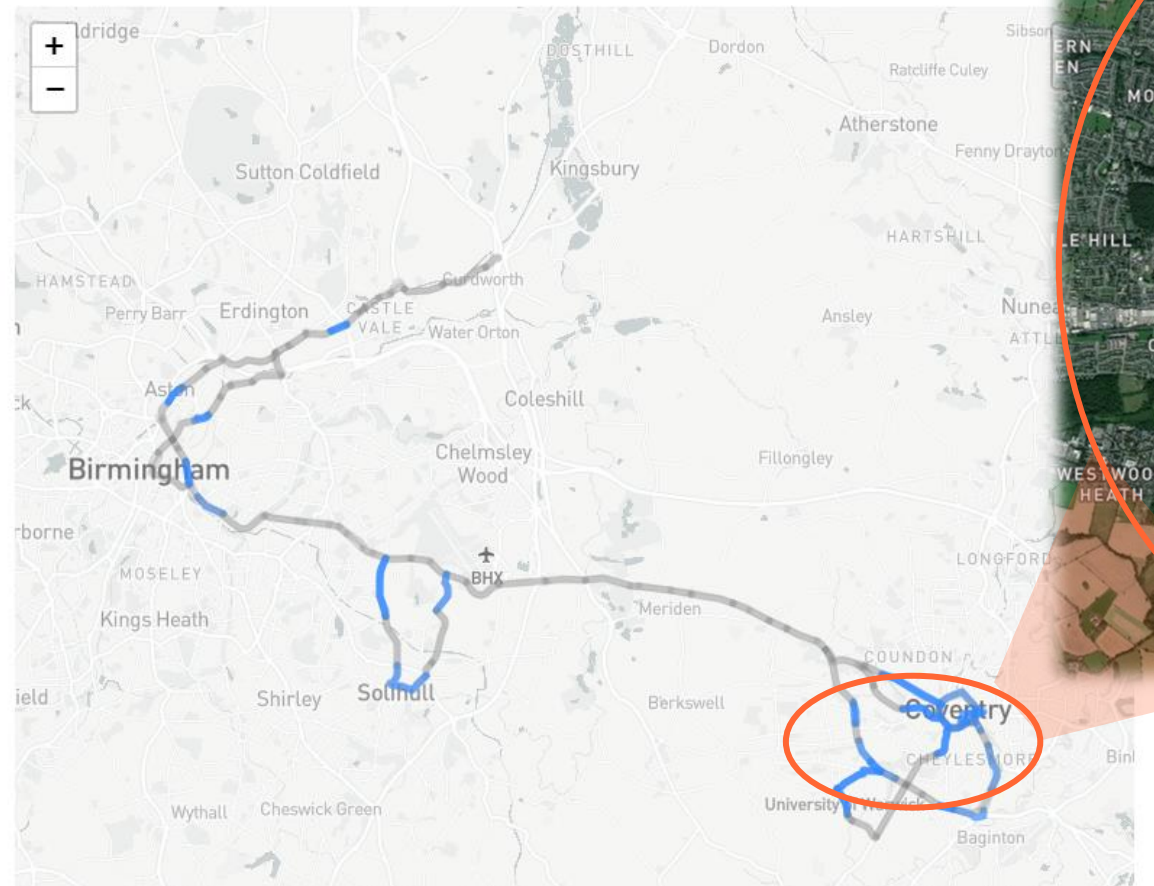
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Tags Definition Files **Route Locations** Versions

Midlands Future Mobility Search 38 possible testing locations found

This testbed does not support all of the tags for this scenario



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Tags Definition Files **Route Locations** Versions

Midlands Future Mobility Search 38 possible

This testbed does not support all of the tags for this scenario

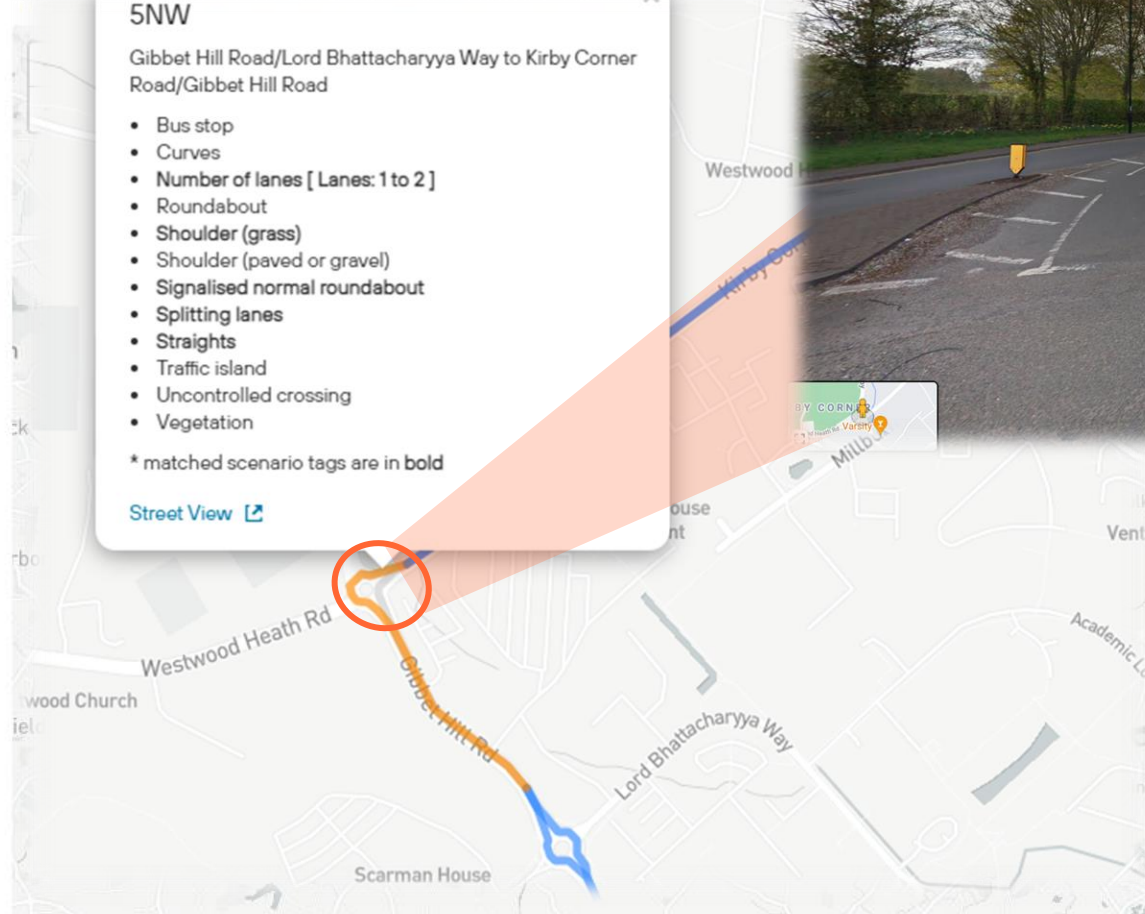
5NW

Gibbet Hill Road/Lord Bhattacharyya Way to Kirby Corner Road/Gibbet Hill Road

- Bus stop
- Curves
- **Number of lanes [Lanes: 1 to 2]**
- Roundabout
- **Shoulder (grass)**
- Shoulder (paved or gravel)
- Signalised normal roundabout
- Splitting lanes
- Straights
- Traffic island
- Uncontrolled crossing
- Vegetation

* matched scenario tags are in bold

[Street View](#)



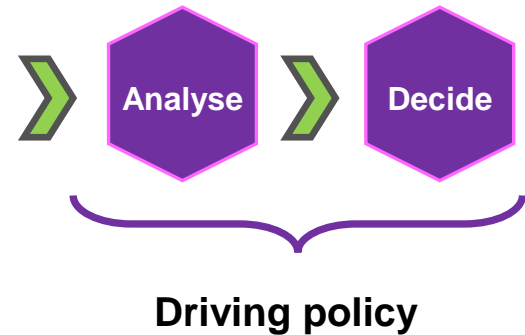
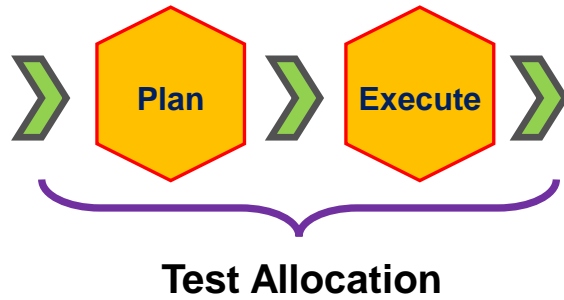
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Evaluation Continuum

Scenarios

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Certification / Safety
Evidence & Argument

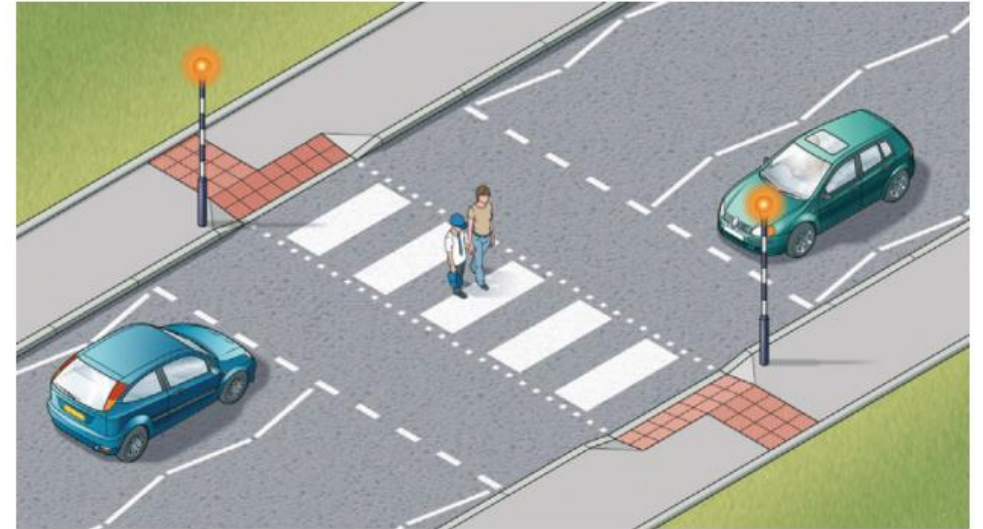


Rules of the Road (for human drivers)

- UK Highway Code (for human drivers) rule defines:
 - Doing some behaviour somewhere
 - NOT doing some behaviour somewhere
- Doing / NOT doing: behaviour competency library
- Somewhere: ODD instantiation

UK Highway Code: Rule 195

“As you approach a zebra crossing: look out for pedestrians waiting to cross and be ready to slow down or stop to let them cross; you MUST give way when a pedestrian has moved onto a crossing”



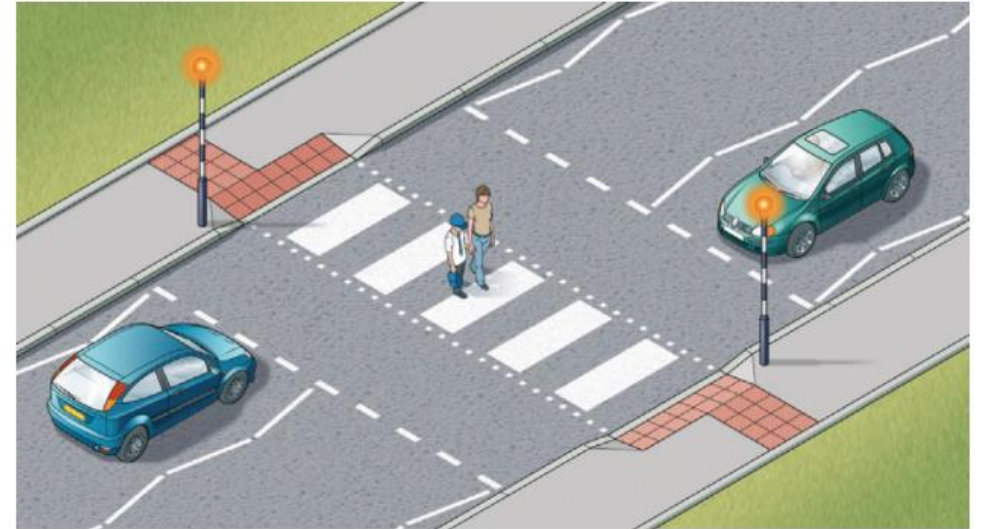
Rule 19: Zebra crossings have flashing beacons

Behaviour

ODD

UK Highway Code: Rule 195

*“As you approach a zebra crossing: look out for pedestrians waiting to cross and be ready to slow down or stop to let them cross; you **MUST** give way when a pedestrian has moved onto a crossing”*



Rule 19: Zebra crossings have flashing beacons

How long to wait?

Behaviour

ODD

Assumptions

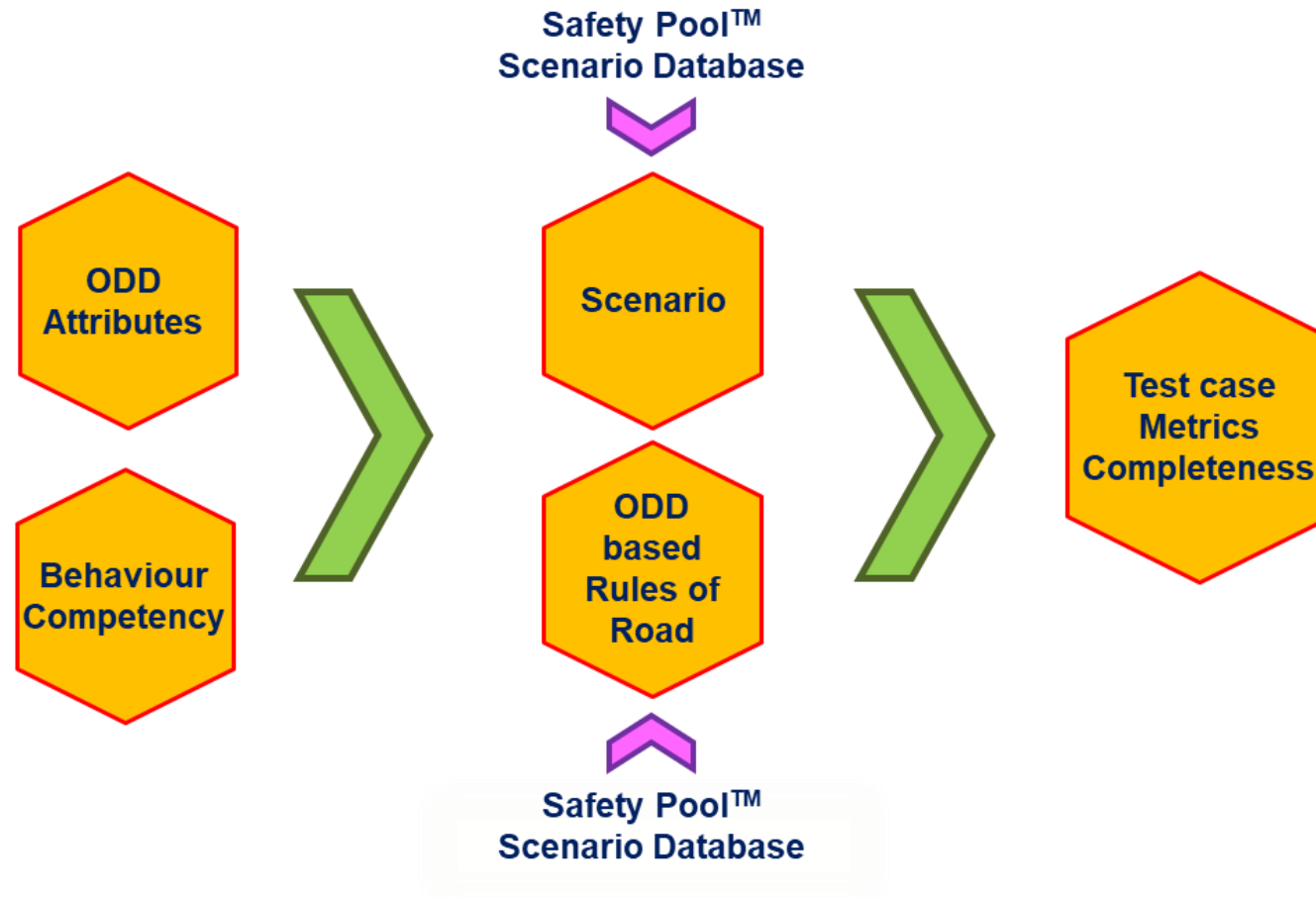
ODD Based Codified Rules of the Road

*Current Rules of Road
(for human drivers)* = $f(\text{Operating condition, Behaviour competency, Assumptions})$



*Codified
Rule of the Road* = $f(\text{Operating condition, behaviour competency, driving characteristics})$

ODD Based Scalable Safety Assurance Framework



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Minimum ODD definition



ODD Definition 1

Motorways

ODD Definition 2

4 lane motorway,
Lane width min. 3m
Sunny days only
Daytime only

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Summary

- Each aspect of safety assurance of ADS needs to consider its relationship with ODD.
- Scenarios need to be a function of their ODD. **Safety metrics** need to be a function of ODD.
- Need for concrete tools and methods to convert philosophical concepts into implementation.
- Success will be dependent upon suitable collaboration, data sharing and **common understanding**, nationally and internationally

Thank you... Discussion...

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